1. Functions

- > Display floor and landing call controller.
- Output arrival gong and arrival light.
- Indicate elevator condition through light emitting diode indicator.
- > Support display of elevator condition and set functions of light emitting diode indicator.
- > Support serial communication input of parking and fire fighting.

2. Dimension

Different model has different dimension, it should refer to final drawing provided by technical Department.

3. Interface definition and technical specification

Name	Position	Definition	Usage	Interface technical specification	
	Position			Interface Type	Rated Load
PW	PW-1	24V power input	Power and communication interface	Power	150mA
	PW-2	GND		Power	
	PW-3	CAN BUS H			
	PW-4	CAN BUS L			
	SH-1	Up call response		Output open-drain	DC24V、20mA
i	SH-2	24V	Up call push		
<u> </u>	CLL 2	01/	button input and	Low voltage	
SH	SH-3	0V	response output	Enable	
		Up call input	7	Resistor	
i	SH-4			distribute	
				voltage	
	XH-1	Down call response		Output	DC24V、20mA
	\(\(\)\(\)			open-drain	DC24V\ 201111
i	XH-2	24V	Down call push		
XH	XH-3	0V	button input and	Low voltage	
ΛΠ	VI 1-2		response output	enable	
		Down call input		Resistor	
4	XH-4			distribute	
	<u> </u>		<u> </u>	voltage	
AN	setting butte	setting button SZ setting jumper			
	Parking jumper. When standby input is set to input of parking & fire state, please set the parking				
DS	jumper ON a	at fire landing.			

Note 1: According to different programs, standby input can be set to parking input, fire input, the handicapped push button or visitor's push button.

Note 2: General program of factory default: Standby input 0 is parking input. Standby input 1 is fire input.